



## NDT&E Methods: UT

6.	NDT&E: Introduction to Methods
6.1.	Ultrasonic Testing: Basics of Elasto-Dynamics
6.2.	Ultrasonic Testing: Ultrasound Generation
6.3.	The Pulse-Echo Method
6.4.	UT-Systems: Transducer, Instrument, Manipulator
6.5.	Current Developments
6.6.	Case Studies by Movies





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## General Considerations and Requirements on potential stress wave sources:

- 1. frequency content control;
- 2. pulse length control (damped pulses)
- 3. magnitude of loading force control
- 4. wave mode generation
- 5. Intensity profile control
- 6. Control of propagation direction



## **NDT&E Methods: Mechanical Impact**

## **Mechanical Impacts**

with solids generate Ultrasound through a linear momentum transfer from the imparting body to the mechanical waves.











# Impact-Echo TestingWave Speed MeasurementCONCRETE Inspection with frequencies up to 80 kHz

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#### Hand-held transducer. Courtesy of Impact-Echo Instruments, LLC.







#### Impact-Echo pistol grip transducer

Courtesy of Impact-Echo Instruments, LLC.





## NDT&E Methods: Ultrasound Generation Laser Impact



**Thermoelastic Regime** 

**Ablative Regime** 

## **Laser Generation of Ultrasound**





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#### **Ultrasonic measurement Scheme**

using a pulsed laser and a Michelson-type interferometer for ultrasound detection

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Ultrasonic Measurement Scheme (Pulsed Laser for Ultrasound Generation, a Michelson-Type Interferometer for Detection) Nondestructive Testing & Evaluation TPU Lecture Course 2015/16



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#### **ADVANTAGES & DISADVANTAGES of LBU**

NONCONTACT	LOWER SENSITIVITY
REMOTE	RELATIVELY EXPENSIVE
RAPID SCANNING	GENERATION EFFICIENCY DEPENDS ON OPTICAL ABSORPTION
SCANNING OF AWKWARD GEOMETRIES	REQUIRES LASER SAFETY PRECAUTIONS
CAN BE A POINT SOURCE Both temporally and spatially	
BROADBAND (Generation & Detection)	
REPRODUCIBLE SOURCE	
GENERATION OF SURFACE & BULK WAVES	
SHAPING OF SURFACE WAVE FRONTS	
ABSOLUTE CALIBRATION BY LASER INTERFEROMETRY	



## NDT&E Methods: Ultrasound Generation *Piezoelectricity - the piezoelectric effect* ("Pressure Electricity")



![](_page_14_Picture_2.jpeg)

## Piezoelectricity - the piezoelectric effect ("Pressure Electricity")

is the appearance of an electrical potential across the sides of a crystal when you subject it to mechanical stress:

## P = ex

with P: Polarization; e: piezoelectric stress coefficient; x: strain

In the converse piezoelectric effect, a crystal becomes mechanically stressed (deformed in shape) when a voltage is applied across its opposite faces:

## $\mathbf{x} = dE$

#### with x: strain, d: piezoelectric strain coefficient, E: electric field

The piezoelectric effect was discovered in 1880 by the brothers Pierre and Paul-Jacques Curie, in crystals of quartz, tourmaline, and Rochelle salt (potassium sodium tartrate). They took the name from the Greek work piezein, which means "to press."

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![](_page_15_Picture_11.jpeg)

It has been discovered that in the 32 crystal classes, which conventionally separated into 7 crystal systems, only 20 classes possesses piezoelectric crystals (Nye, 1972).

Only the crystal classes that possess no center of symmetry are the ones have piezoelectricity. The dipoles form groups of atoms in the lattice are the cause of the asymmetric crystal to have the piezoelectric effects.

> Examples of piezo electric cystals: Quartz the synthetic ceramic, lead zirconate, titanate.

![](_page_16_Picture_4.jpeg)

![](_page_17_Figure_1.jpeg)

![](_page_18_Figure_1.jpeg)

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![](_page_19_Picture_1.jpeg)

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![](_page_19_Picture_4.jpeg)

![](_page_20_Figure_1.jpeg)

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## NDT&E Methods: Ultrasound Generation Poling Process of Ferroelectrica

![](_page_21_Figure_1.jpeg)

![](_page_21_Picture_2.jpeg)

The vector P in the diagram points in the direction of the net dipole resulting from the displacement of charge.

## Lattice of Pb(TiO<sub>2</sub>)

![](_page_21_Picture_5.jpeg)

![](_page_22_Picture_1.jpeg)

![](_page_22_Picture_2.jpeg)

The dipoles in macroscopic sample can have random orientations in which case the material has no net moment Applying a strong electric field aligns the dipoles. The oriented dipolar domains can loose their structure at high temperature, with wear etc.

#### Poled ferroelectric materials form materials which are *piezoelectric*

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![](_page_22_Picture_8.jpeg)

**Mathematical Description** 

Linear piezoelectricity is the combined effect of the linear electric behavior of the material and Hook's law for linear elastic materials:

$$D = \varepsilon E \text{ with } \nabla D = 0 \text{ and } \nabla x E = 0$$
  
$$S = ST \text{ with } \nabla T = 0 \text{ and } S = (\nabla u + u\nabla)$$

D: Electric Charge Density Displacement, *ɛ:* Permittivity, E: Electric Field Strength

S: Strain, s: Compliance, T: Stress

Combined > STRAIN CHARGE FORM:

 $S = ST + d^t E$  (d<sup>t</sup>: Matrix for the converse effect)  $D = dT + \varepsilon E$  (d: Matrix for the direct effect)

![](_page_23_Picture_10.jpeg)

Ultrasound is generated with a transducer.

A piezoelectric element in the transducer converts electrical energy into mechanical vibrations (sound), and vice versa.

![](_page_24_Picture_3.jpeg)

The transducer is capable of both transmitting and receiving sound energy.

![](_page_24_Picture_7.jpeg)

![](_page_25_Figure_1.jpeg)

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![](_page_25_Picture_4.jpeg)

![](_page_25_Picture_5.jpeg)

## NDT&E Methods: Ultrasound Generation What is an Ultrasonic Transducer?

A transducer is any device that converts one form of energy to another.

![](_page_26_Figure_2.jpeg)

An ultrasonic transducer converts electrical energy to mechanical energy, in the form of sound, and vice versa (Olympus).

The main components of a piezo-transducer are:

- The active element
  - The backing
  - The wear plate

![](_page_26_Picture_8.jpeg)

#### The **active element**

is commonly a polarized ceramics. It can be cut in a variety of manners to produce different wave modes.

#### The **backing**

Is usually a highly attenuative, high density material. It is used to control the vibration of the transducer by absorbing the energy radiation from the back face of the active element. When the acoustic impedance matches the impedance of the active element, the transducer is highly damped.

# 

#### The wear plate

protects the transducer active element. It serves as an acoustic transformer between the active element and the media (water, Perspex, etc) of lower acoustic impedance. This is accomplished by selecting a matching layer of ¼ wavelength thickness. The waves generated by the active element of ½ wavelength thickness are in phase with the wave reverberating in the matching layer.

When signals are in phase, their amplitudes are additive.

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![](_page_27_Picture_11.jpeg)

## NDT&E Methods: Ultrasound Generation Lorentz Force

# $\mathbf{F} = q \left[ \mathbf{E} + (\mathbf{v} \times \mathbf{B}) \right]$

A combination of electric and magnetic force on a point charge due to electromagnetic fields

![](_page_28_Picture_3.jpeg)

![](_page_28_Picture_5.jpeg)

![](_page_28_Picture_6.jpeg)

![](_page_29_Figure_0.jpeg)

 $\mathbf{F}(z) = (\mathbf{j}(z) \ge \mathbf{B}_0)/n_0$ 

Speed, density

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## NDT&E Methods: EMAT

![](_page_30_Figure_1.jpeg)

## s: Sound velocity d: Density

![](_page_30_Picture_5.jpeg)

![](_page_31_Figure_1.jpeg)

![](_page_31_Picture_2.jpeg)

![](_page_31_Picture_4.jpeg)

## Basic Components in EMAT Transducer There are two basic components in an EMAT transducer.

- a magnet
- an electric coil.

**The magnet** can be a permanent magnet or an electromagnet, which produces a static or a quasi-static magnetic field. In EMAT terminology, this field is called bias magnetic field.

# **The electric coil** is driven with an AC electric signal at frequency, typically in the range from 20 kHz to 10 MHz.

Based on the application needs, the signal can be a continuous wave, a spike pulse, or a tone-burst signal. The electric coil with AC current also generates an AC magnetic field. When the test material is close to the EMAT, ultrasonic waves are generated in the test material through the interaction of the two magnetic fields.

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![](_page_32_Picture_9.jpeg)

The electric coil with AC current also generates an AC magnetic field. When the test material is close to the EMAT, ultrasonic waves are generated in the test material through the interaction of the two magnetic fields.

![](_page_33_Picture_2.jpeg)

![](_page_33_Picture_3.jpeg)

## Based on the application needs, the signal can be a continuous wave, a spike pulse, or a tone-burst signal.

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![](_page_33_Picture_7.jpeg)

![](_page_34_Picture_1.jpeg)

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![](_page_34_Picture_4.jpeg)

#### Effect of Air Gap (Lift-off and Tilt)

![](_page_35_Figure_2.jpeg)

![](_page_35_Picture_3.jpeg)

![](_page_35_Picture_5.jpeg)

## NDT&E Methods: Ultrasound Generation A MASTERTHESIS

D. Rueter, T. Morgenstern. *Ultrasound generation with high power and coil only EMAT concepts,* Ultrasonics vol.
54, issue 8, Elsevier, 2014

#### **Our intention**

- is the investigation of powerful and magnetically induced (non-contact) ultrasound at notably higher frequencies (i.e., >1 MHz instead of 300 kHz or less), suitable for NDT.
- Furthermore, increased lift off distances towards 1 cm instead of just 1 mm or less are approached, interesting for more or new application fields like prepackaged products.

#### The approach

- via magnetic pressure appears to be more convenient here and it still reasonably describes the actual findings from experiments.
- The underlying physics is viewed under the terminology *magnetic pressure* (more common in EMF technologies) instead of explicitly evaluating eddy currents and Lorentz forces (as typically done in EMAT considerations).

![](_page_36_Picture_10.jpeg)

![](_page_37_Picture_1.jpeg)

![](_page_37_Figure_2.jpeg)

A simple LC-Oscillation Circuit

**Characteristic Frequency:** 

 $\frac{1}{2\pi\sqrt{LC}}$ 

 $E = 1/2 CU^2$ 

stored Energy in the Capacitor

## $E = 1/2 LI_{el}^{2}$

for ideal elements the stored Energy in the Capacitor is fully converted into a magnetic field of the inductor L with discharge current I<sub>el</sub>

## **Electric Impedance**

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![](_page_38_Figure_1.jpeg)

![](_page_38_Picture_2.jpeg)

## Magnetic Pressure p

equals the energy density of an oscillating transient magnetic field

$$p = \frac{1}{2} \frac{B^2}{\mu_0} \qquad \qquad F \sim B \\ I_{EC} \sim B$$

## **Effective Sound Intensity**

The effective sound intensity I of an ultrasound wave at sound pressure p (peak value) in a material is:

$$I = \frac{p^2}{2Z_M}$$
 (Z  $\mathbb{P}_{M_1}$ : Acoustic Impedance)

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![](_page_39_Picture_9.jpeg)

# FINAL GENERATED ULTRASOUND POWER $P_{US} = \frac{1}{32} \frac{1}{Z_M A} \left(\frac{E}{g}\right)^2$

# EFFICIENCY $\eta = \frac{1}{32} \frac{1}{\pi \mu_0} \frac{B^2}{Z_M g f}$

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![](_page_40_Picture_5.jpeg)

![](_page_41_Picture_1.jpeg)

![](_page_41_Picture_2.jpeg)

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![](_page_41_Picture_5.jpeg)

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## NDT&E Methods: Ultrasound Generation **MAGNETOSTRICTIVE EFFECT**

Ferromagnetic materials change their shape or dimensions during the process of magnetization.

![](_page_42_Picture_2.jpeg)

The reciprocal effect, the change of the susceptibility (response to an applied field) of a material when subjected to a mechanical stress, is called the Villari effect.

 $\lambda$ : magnetostriction **Le Chatelier's Principle**  $\left(\frac{d\lambda}{dH}\right)_{\sigma} = \left(\frac{dB}{d\sigma}\right)_{H}^{H: magnetizing field strength}$ B: flux density  $_{H}$   $\sigma:$  mechanical stress

![](_page_42_Picture_7.jpeg)

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Total Force exerted on a membrane of a capacitor

![](_page_43_Picture_2.jpeg)

A: Area; V: applied dc voltage; x: membrane displacement; d<sub>0</sub>: initial gap height

#### **EQUILIBRIUM CONDITION:**

Electrical force balances mechanical restoring force  $F_{mech} = kx$ Relation between the membrane displacement and applied dc voltage

$$V = \sqrt{\frac{2kx}{A\varepsilon_0}}(d_0 - x)$$

![](_page_43_Picture_8.jpeg)

![](_page_44_Figure_1.jpeg)

**Transmit Mode** 

**Receive Mode** 

## **Electrical Circuits to Drive CMUTs**

![](_page_44_Picture_5.jpeg)

![](_page_44_Picture_7.jpeg)

![](_page_45_Figure_1.jpeg)

#### **Cross-sectional Schematic Drawing of Membrane**

![](_page_45_Picture_3.jpeg)

![](_page_45_Picture_4.jpeg)

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![](_page_46_Picture_1.jpeg)

## Optical Picture of 2D Array Element that is 400μm by 400μm in size. It Consists of 76 membranes which are 36 μm in Diameter.

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![](_page_46_Picture_5.jpeg)

## NDT&E Methods: UT

## Literature

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![](_page_47_Picture_7.jpeg)