Quick sorting

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Outline

- Data structures
- Insertion sorting (Shell algorithm)
- Heapsort
- Quick sorting (Hoare algorithm)
- Merge sorting
- Stability

- An array can be defined as an ordered collection of items indexed by contiguous integers.
- Random access to elements.
- A[i]:
 - ► A array
 - ▶ i−index
 - A[i] element

C	}	1	2	3	4	5	6	7	8	9	10	11
13	2	45	27	14	78	67	84	91	17	32	83	53

- An array can be defined as an ordered collection of items indexed by contiguous integers.
- Random access to elements (O(1)).
- A[i]:
 - ► A array
 - ▶ i−index
 - > A[i] element

0	1	2	3	4	5	6	7	8	9	10	11
12	45	27	14	78	67	84	91	17	32	83	53

- Linked list is a linear collection of data elements, whose order is not given by their physical placement in memory. Instead, each element points to the next.
- Sequential access (O(n)).



- A data file is a computer file which stores data. File is a linear collection of data elements. It is placed in the file storage.
- Sequential access (O(n)).

12	45	27	14	78	67	84	91	17	32	83	53
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Insertion sort

Idea. At each iteration, insertion sort removes one element from the input data, finds the location it belongs within the sorted list, and inserts it there. It repeats until no input elements remain.



Insertion sort

Pseudocode

- ▶ i ← 1
- while i < length(A)</pre>
 - ▶ x ← A[i]
 - ▶ j ← i 1
 - while j >= 0 and A[j] > x
 - ▶ A[j+1] ← A[j]

> end while

- ► A[j+1] ← X
- ▶ i ← i + 1
- end while

Insertion sort

- Computational complexity:
- Worst case: N² (array is in the reverse order, (i-1) shifts for A[i]).
- **Best case**: N (Array is ordered).
- Data structures: array, doubly linked list

- Shell, D. L. (1959). "A High-Speed Sorting Procedure". Communications of the ACM. 2 (7): 30–32.
- Idea:
- Divide an array into h subarrays, with the gap h.
- Sort every subarray using insertion.
- Decrease h.
- Repeat until h=1.







- First (for big gaps) arrays are short
- Then (for small gaps) small number of shifts



Gap sequence

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It's a kind of magic (Donald Knuth).

General term	Gaps	Worst-case complexity	Authors

The (binary) heap data structure is an array object that we can view as a nearly complete binary tree (the height is NlnN).



Heap property

 $a \ i \geq \max \ a \ 2i+1$, $a \ 2i+2$



 Williams, J. W. J. (1964), "Algorithm 232 - Heapsort", Communications of the ACM, 7 (6): 347–348,

HEAPIFY (maintaining heap property)



HEAPIFY (maintaining heap property)

Complexity O(In N)



- BUILDHEAP (construction a heap using HEAPIFY)
- Complexity O(N/2)
- ▶ j = N/2-1
- > Use HEAPIFY(j)
- ▶ j=j-1
- ▶ Until j<0













HEAPSORT

- Swap A[0] and A[N-1] (the maximum element becames the last
- ▶ N=N-1
- Restore the heap property for A[0]...A[N-1] by using HEAPIFY(0)
- Until N=0
- Complexity NlnN

HEAPSORT















- Hoare, C. A. R. (1961). "Algorithm 64: Quicksort". Comm. ACM.
 4 (7): 321.
- ldea.
- Pick an element, called a *pivot*, from the array.
- Partitioning: reorder the array so that all elements with values less than the pivot come before the pivot, while all elements with values greater than the pivot come after it (equal values can go either way).
- Recursively apply the above steps to the sub-array of elements with smaller values and separately to the sub-array of elements with greater values.





i > j

Recursive calls (L,j) and (I,R)







i

i



8	9	10	11
91	84	83	53
8	9	10	11
91	84	83	53
i			j
8	9	10	11
53	84	83	91
	i	J	
8	i 9	j 10	11
8 53	i 9 84	J 10 83	11 91
8 53	i 9 84 i	j 10 83 j	11 91
8 53 8	i 9 84 i 9	j 10 83 j 10	11 91 11
8 53 8 53	i 9 84 i 9 83	j 10 83 j 10 84	11 91 11 91

М

R

8

9	10	11	
83	84	91	

Divide-and-conquer



Direct merge sorting

0	1	2	3	4	5	6	7	8	9	10	11	
12	32	27	14	17	38	84	91	45	45	83	53	Divide

0	1	2	3	4	5
12	27	17	84	45	83
0	1	2	3	4	5
32	14	38	91	45	53



Merge

0	1	2	3	4	5	6	7	8	9	10	11
12	32	14	27	17	38	84	91	45	45	53	83
0	1	2	3	4	5						
12	32	17	38	45	45						
0	1	2	3	4	5						
14	27	84	91	53	83						
0	1	2	3	4	5	6	7	8	9	10	11
12	14	27	32	17	38	84	91	45	45	53	83

0	1	2	3	4	5	6	7	8	9	10	11
12	14	27	32	17	38	84	91	45	45	53	83
0	1	2	3	4	5	6	7	_			
12	14	27	32	45	45	53	83				
0	1	2	3								
17	38	84	91								
0	1	2	3	4	5	6	7	8	9	10	11
12	14	17	27	32	38	84	91	45	45	53	83

0	1	2	3	4	5	6	7	8	9	10	11
12	14	17	27	32	38	84	91	45	45	53	83
0	1	2	3	4	5	6	7				
12	14	17	27	32	38	84	91				
0	1	2	3								
45	45	53	83								
				1							
-					_	•	_		•	10	
0	1	2	3	4	5	6	7	8	9	10	11
12	14	17	27	32	38	45	45	53	83	84	91

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Natural merge: use decreasing subarrays









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	Mer	ge	pha	ise												
0	1	2														
12	27	32								0	1	2				
	Х								X>Y	12	14	17				
0	1	2	3	4	5	6	7			12	. 14					
14	17	38	45	45	83	84	91									
	Y															
				, .												
			1	2 2	7 3	2							0	1	2	3
				>	<							X≤Y	12	14	17	2
			C) 1	1 2	2 3	4	5	6	7						
			1	4 1	7 3	8 45	45	83	84	91						
					Y	/										



Equal elements keep their initial order in a sorted array

0	1	2	3	4	5	6
12	14	27	14	17	27	84











Heapsort is unstable





Quicksort





Quicksort is unstable

0	1	2	3	4	5	6
12	14	27	14	17	27	84
0	1	2	3	4	5	6
12	14	14	17	27	27	84

Mergesort is stable

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Merge sorting for linked lists









Merge sorting for linked lists







Comparison

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	Worst case	Average case	Data structures	Stability
Shell	N ²		Random access	No
Hepsort	N logN	N logN	Random access	No
Quicksort	N ² (hardly ever possible)	N logN	Random access	No
Mergesort	N logN	N logN	Random access Sequential access	Yes