

Fredholm Integral Equations with Degenerate Kernel

Integral Equations with Degenerate Kernel

The *Degenerate (or separable) kernel* of 2nd kind Fredholm integral equation is the kernel $K(x,t)$ of a finite sum of products of functions depending only on x and t , respectively. Mathematically, this can be written

$$K(x,t) = \sum_{k=1}^n a_k(x) \cdot b_k(t). \quad (1)$$

It is assumed in the formula (1) that the functions $a_k(x)$ and $b_k(t)$ ($k = 1, 2, \dots, n$) are continuous in the domain $a \leq x, t \leq b$ and are linearly independent among themselves.

In this case, the integral equation with degenerate kernel (1) can be written in the form

$$\varphi(x) - \lambda \int_a^b \left[\sum_{k=1}^n a_k(x) \cdot b_k(t) \right] \varphi(t) dt = f(x). \quad (2)$$

To obtain a solution of the equation (2) it could be rewritten in form

$$\varphi(x) = f(x) + \lambda \sum_{k=1}^n a_k(x) \int_a^b b_k(t) \varphi(t) dt \quad (3)$$

By introducing the notation

$$\int_a^b b_k(t) \varphi(t) dt = C_k \quad (k = 1, 2, \dots, n), \quad (4)$$

the formula (3) could be written

$$\varphi(x) = f(x) + \lambda \sum_{k=1}^n C_k a_k(x), \quad (5)$$

where C_k — is unknown constants. This is a consequence of the fact that the expressions for C_k include the unknown function $\varphi(x)$. It follows from the calculations that is sufficient to find the C_k ($k = 1, 2, \dots, 3$) in order to obtain the solution to integral equations with degenerate kernel. To do this, one may substitute the expression (5) into the equation (2) and after simple transformations one can obtain

$$\sum_{m=1}^n \left\{ C_m - \int_a^b b_m(t) \left[f(t) + \lambda \sum_{k=1}^n C_k a_k(t) \right] dt \right\} a_m(x) = 0$$

Since the coefficients $a_m(x)$ ($m = 1, 2, \dots, n$) are linearly independent, the last expression can be written

$$C_m - \int_a^b b_m(t) \left[f(t) + \lambda \sum_{k=1}^n C_k a_k(t) \right] dt = 0,$$

or

$$C_m - \lambda \sum_{k=1}^n C_k \int_a^b a_k(t) b_m(t) dt = \int_a^b b_m(t) f(t) dt \quad (m = 1, 2, \dots, n).$$

By introducing the notation

$$a_{km} = \int_a^b a_k(t) b_m(t) dt, \quad f_m = \int_a^b b_m(t) f(t) dt,$$

one can obtain

$$C_m - \lambda \sum_{k=1}^n a_{km} C_k = f_m, \quad (m = 1, 2, \dots, n)$$

It is more convenient to write the last expression in the form of a system of equations

$$\left\{ \begin{array}{l} (1 - \lambda a_{11})C_1 - \lambda a_{12}C_2 - \cdots - \lambda a_{1n}C_n = f_1 \\ -\lambda a_{21}C_1 + (1 - \lambda a_{22})C_2 - \cdots - \lambda a_{2n}C_n = f_2 \\ \dots\dots\dots \\ -\lambda a_{n1}C_1 - \lambda a_{n2}C_2 - \cdots + (1 - \lambda a_{nn})C_n = f_n \end{array} \right. \quad (6)$$

To solve the system (6), i.e. finding the coefficients C_k it is necessary to solve a system of n linear equations with n unknowns.

To do this, it is necessary to find out, at first, what the determinant of a given system is equal to. It could be written as

$$\Delta(\lambda) = \begin{vmatrix} 1 - \lambda a_{11} & -\lambda a_{12} & \cdots & -\lambda a_{1n} \\ -\lambda a_{21} & (1 - \lambda a_{22}) & \cdots & -\lambda a_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ -\lambda a_{n1} & -\lambda a_{n2} & \cdots & (1 - \lambda a_{nn}) \end{vmatrix} \quad (7)$$

If $\Delta(\lambda) \neq 0$ than the system of equation (6) has a unique solution and coefficients C_k can for example be found by using Cramer's rule

$$C_k = \frac{1}{\Delta(\lambda)} \begin{vmatrix} 1 - \lambda a_{11} & \cdots & -\lambda a_{1k-1}f_1 - \lambda a_{1k+1} & \cdots & -\lambda a_{1n} \\ -\lambda a_{21} & \cdots & -\lambda a_{2k-1}f_2 - \lambda a_{2k+1} & \cdots & -\lambda a_{2n} \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ -\lambda a_{n1} & \cdots & -\lambda a_{nk-1}f_n - \lambda a_{nk+1} & \cdots & 1 - \lambda a_{nn} \end{vmatrix} \quad (8)$$

In this case solution of equation (2) is the function $\varphi(x)$ is described by the expression

$$\varphi(x) = f(x) + \lambda \sum_{k=1}^n C_k a_k(x),$$

where C_k ($k = 1, 2, \dots, n$) is coefficients are coefficients determined by formula (8).