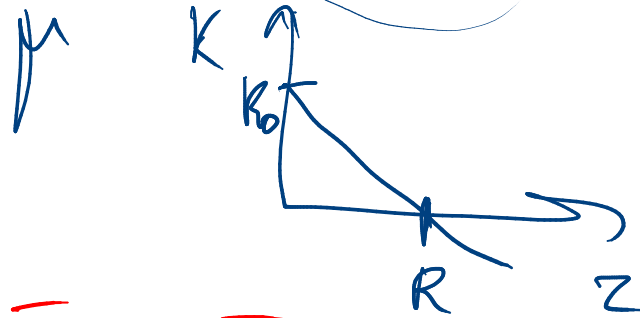


$$k = k_0 \left(1 - \frac{z}{R} \right)$$



$$\vec{F} = m\vec{a}$$

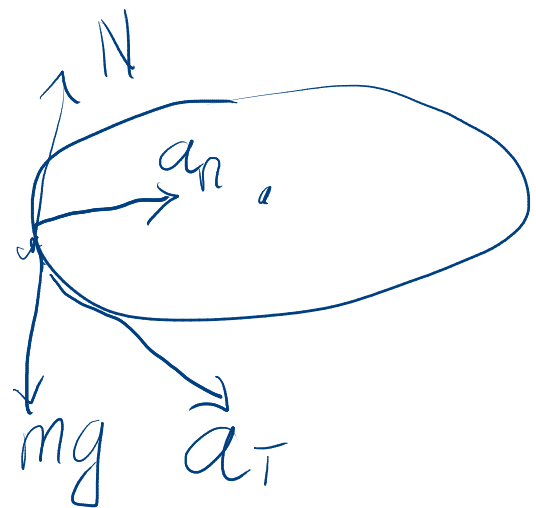
$$\vec{N} + m\vec{g} + \vec{F}_{TP} = m\vec{a}, \quad a = \frac{v^2}{R}$$

$$\downarrow \quad \downarrow$$

$$N = mg$$

$$F_{TP} = ma = m \frac{v_{max}^2}{R}$$

$$F_{TP} = kN = kmg$$



\Rightarrow

$$\vec{m}\vec{a} = \vec{F}_{mp} + \vec{m}\vec{g} + \vec{N}$$

$$N = mg$$

$$ma_n = F_{mp} = kmg = m \frac{v_{max}^2}{R}$$

$$v_{max}^2 = \frac{kRg}{2} \Rightarrow S = \frac{kRg}{2a_t}$$

$$v_{max}^2 - v_0^2 = 2a_t s$$

\Rightarrow

$$2as =$$

$$kRg$$

\Rightarrow

$$S = \frac{kRg}{2a_t}$$

$$\vec{F} = m\vec{a} = m \frac{d\vec{v}}{dt} = \frac{d(m\vec{v})}{dt} = \frac{d\vec{p}}{dt}$$

$$\vec{F} = \frac{d\vec{p}}{dt} = \vec{a} t (\hat{i} - t)$$

$$d\vec{p} = (\vec{a} t \hat{i} - \vec{a} t^2) dt$$

$$\Delta \vec{p} = \vec{a} \hat{i} \frac{t^2}{2} - \vec{a} \frac{t^3}{3}$$

$$\vec{p} = p_0 +$$

$$\vec{p}(\tau) = 0 + \vec{a} \hat{i} \frac{\tau^2}{2} - \vec{a} \frac{\tau^3}{3} = \vec{a} \hat{i} \frac{\tau^3}{6}$$

2) $S = ?$ $v = \frac{dS}{dt}$

$$S = \int_0^{\tau} v dt$$

$$v = \frac{F}{m}$$

$$S =$$

$$k \text{ mag} = \frac{v^2}{z}$$

$$v^2 = k_0 \left(z - \frac{z^2}{R} \right) g$$

$$v = v(z)$$

$v_{\text{max}} - ?$

$$v' = 0$$

$z_{\text{max}} - ?$

$$= \frac{R}{2} \leftarrow$$

$$v\left(\frac{R}{2}\right) = \sqrt{k_0 g \left(\frac{R}{2} - \frac{R}{4} \right)} = v_{\text{max}}$$

$$= \sqrt{k_0 g \frac{R}{4}} = \sqrt{k_0 g R} / 2$$

$$z_{\text{max}} = \frac{R}{2}$$

$$k = k_0 \left(1 - \frac{z}{R} \right)$$

$$g k = \frac{v^2}{z}$$

$$g z k = v^2$$

$$g k_0 \left(z - \frac{z^2}{R} \right) = v^2$$

